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TITLE: TEACHING DEVICE OF ROBOT
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INVENTOR-INFORMATION:

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ABSTRACT:

PURPOSE: To teach a robot easily for a short period by controlling three light emitting sources and two position detectors periodically to control the operation of detected information and the robot.

CONSTITUTION: A position detector PSD camera controller PCC controls the position detecting operations of position detectors PSD1, PSD2 and the light emitting operations of light emission diodes LEDs 1~3 periodically, and also calculates the position and posture of a glove G on the basis of the detected information by the position detectors PSD1, PSD2. An A/D converter AD converts these calculated values into digital values and inputs the digital values to a robot controller RC to apply commands for the position, posture and the opening width H of the hand to the robot R on the basis of a command outputted from a control box CB.

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